

Lecture 21 (Data Structures 5)

Priority Queues and Heaps

CS61B, Spring 2024 @ UC Berkeley

Slides credit: Josh Hug



Introducing the Priority Queue

Lecture 21, CS61B, Spring 2024

Priority Queue Introduction

- Introducing the Priority Queue
- Using a PQ
- Some Bad Implementations

Heaps

- Heap Definitions
- Heap Add
- Heap Delete

Tree Representations

- Recursive Representation (1)
- Array Representations (2, 3, 3b)

Priority Queue Summary Data Structures Summary



```
/** (Min) Priority Queue: Allowing tracking and removal of the
  * smallest item in a priority queue. */
public interface MinPQ<Item> {
   /** Adds the item to the priority queue. */
   public void add(Item x);
   /** Returns the smallest item in the priority queue. */
   public Item getSmallest();
   /** Removes the smallest item from the priority queue. */
   public Item removeSmallest();
   /** Returns the size of the priority queue. */
   public int size();
}
```

Useful if you want to keep track of the "smallest", "largest", "best" etc. seen so far.



Using a PQ

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Suppose we have a particle detector that records the energy of incoming particles.

Suppose we want to record the M highest energy particles in a given day.

Naive approach: Create a list of all particles detected during the day. Sort it using a particle energy comparator. Return the M particles that have highest energy.



```
public List<Particle> highestEnergyParticles(Detector det, int M) {
    ArrayList<Particle> allParticles = new ArrayList<>();
```

```
for (Timer timer = new Timer(); timer.hours() < 24; ) {
    allParticles.add(det.getNextParticle());</pre>
```

```
Comparator<String> cmptr = new EnergyComparator();
Collections.sort(allParticles, cmptr, Collections.reverseOrder());
```

```
return allParticles.sublist(0, M);
```

```
}
```

}

Potentially uses a huge amount of memory $\Theta(N)$, where N is number of particles.



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public List<Particle> highestEnergyParticles(Detector det, int M) {
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Potentially uses a huge amount of memory $\Theta(N)$, where N is number of particles.

• Goal: Do this in $\Theta(M)$ memory using a MinPQ.

MinPQ<Particle> highEnergyParticles = new HeapMinPQ<>(cmptr);



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public List<Particle> highestEnergyParticles(Detector det, int M) {
    Comparator<Particle> cmptr = new EnergyComparator();
    MinPQ<Particle> highEnergyParticles = new HeapMinPQ<>(cmptr);
    for (Timer timer = new Timer(); timer.hours() < 24; ) {
        // Do something with det.getNextParticle(); ??
    ...
}</pre>
```

Potentially uses a huge amount of memory $\Theta(N)$, where N is number of particles.

• Goal: Do this in $\Theta(M)$ memory using a MinPQ.

MinPQ<Particle> highEnergyParticles = new HeapMinPQ<>(cmptr);



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    Comparator<Particle> cmptr = new EnergyComparator();
    MinPQ<Particle> highEnergyParticles = new HeapMinPQ<>(cmptr);
    for (Timer timer = new Timer(); timer.hours() < 24; ) {</pre>
        highEnergyParticles.add(det.getNextParticle());
        if (highEnergyParticles.size() > M)
           { highEnergyParticles.removeSmallest(); }
   ArrayList<String> returnList = new ArrayList<String>();
    while (highEnergyParticles.size() > 0) {
            returnList.add(highEnergyParticles.removeSmallest());
    }
    return returnList;
```

Can track top M transactions using only M memory. API for MinPQ also makes code very simple (don't need to make explicit comparisons).



Some Bad Implementations

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Some possibilities:

- Ordered Array
- Bushy BST: Maintaining bushiness is annoying. Handling duplicate priorities is awkward.
- HashTable: No good! Items go into random places.

	Ordered Array	Bushy BST	Hash Table	Неар
add	Θ(N)	Θ(log N)	Θ(1)	
getSmallest	Θ(1)	Θ(log N)	Θ(N)	
removeSmallest	Θ(N)	Θ(log N)	Θ(N)	
Caveats		Dups tough		



Heap Definitions

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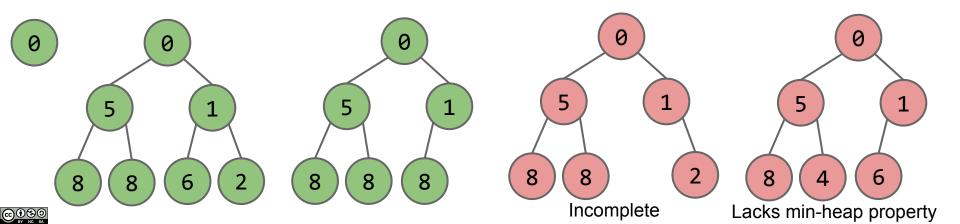
Priority Queue Summary Data Structures Summary



BSTs would work, but need to be kept bushy and duplicates are awkward.

Binary min-heap: Binary tree that is *complete* and obeys *min-heap property*.

- Min-heap: Every node is less than or equal to both of its children.
- Complete: Missing items only at the bottom level (if any), all nodes are as far left as possible.



Heap Comprehension Test: yellkey.com/true

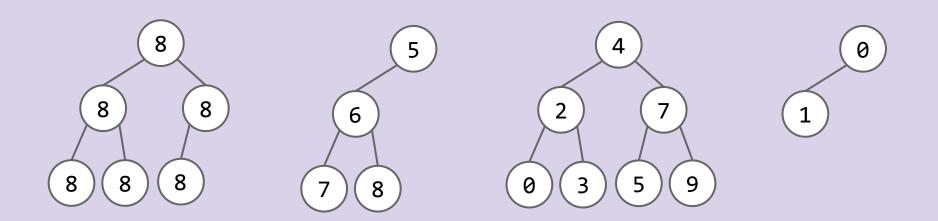
How many of these are min heaps?

A. 0

B. 1

C. 2

- D. 3
- E. 4



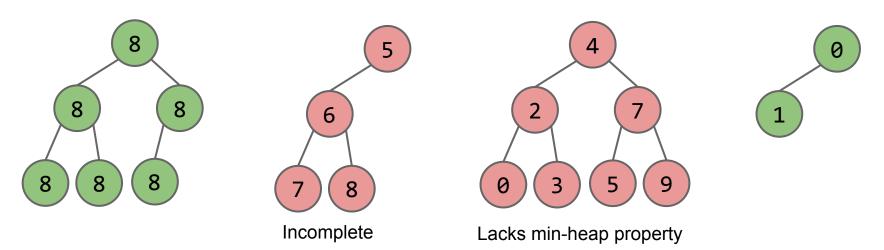


Heap Comprehension Test

How many of these are min heaps?

A. 0

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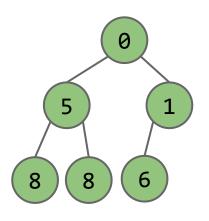




Heaps lend themselves very naturally to implementation of a priority queue.

Hopefully easy question:

• How would you support getSmallest()?





Heap Add

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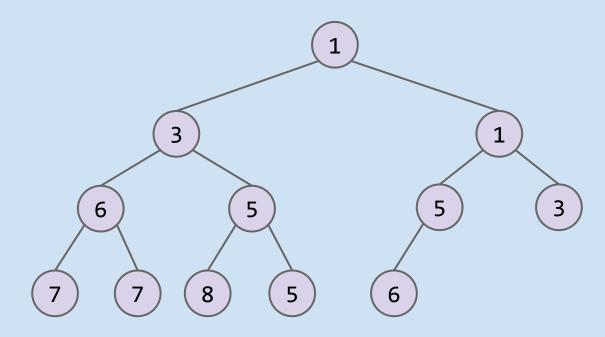


How Do We Add to a Heap?

Challenge: Come up with an algorithm for add(x).

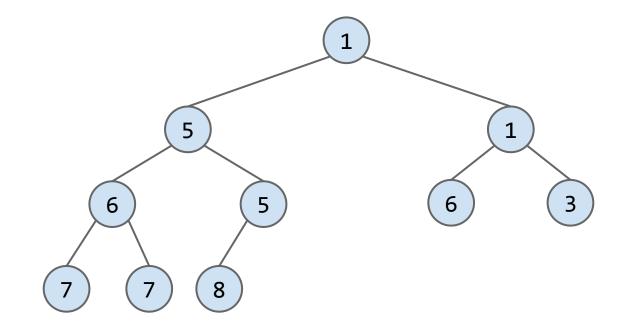
• How would we insert 3?

Runtime must be logarithmic.



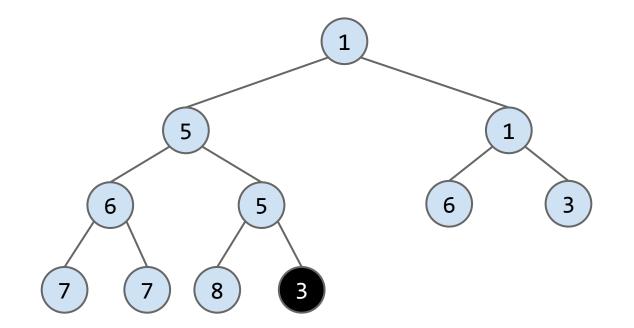


Heap Add Demo



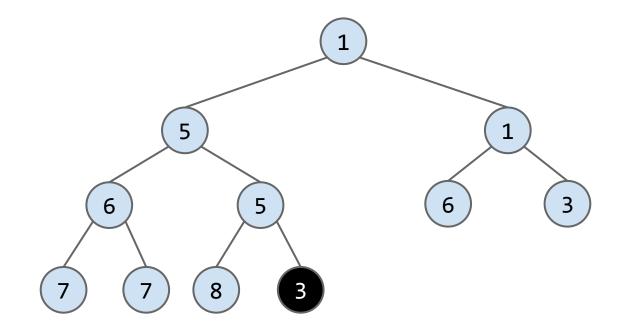
Insert 3?





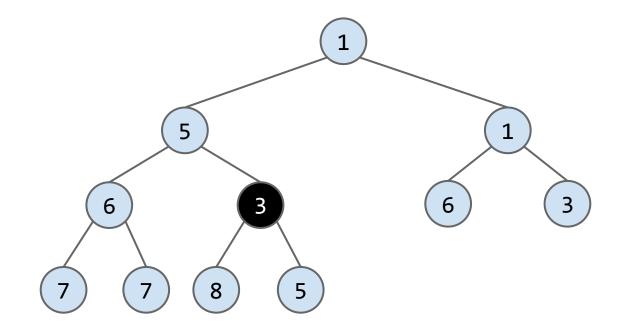
• Add to end of heap temporarily.





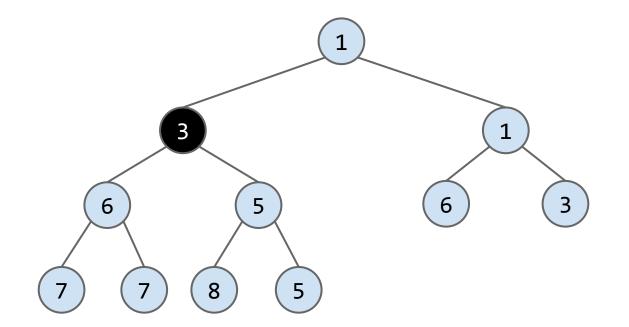
- Add to end of heap temporarily.
- Swim up the hierarchy to your rightful place...





- Add to end of heap temporarily.
- Swim up the hierarchy to your rightful place...

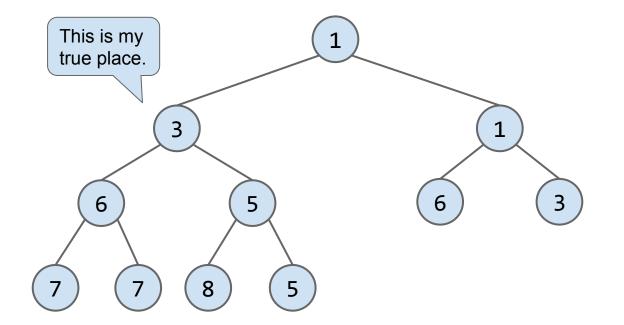




- Add to end of heap temporarily.
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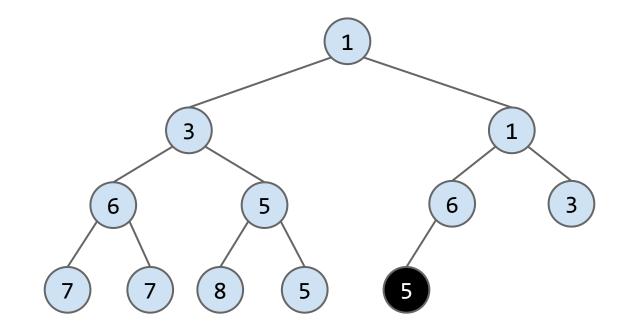


Heap Add Demo



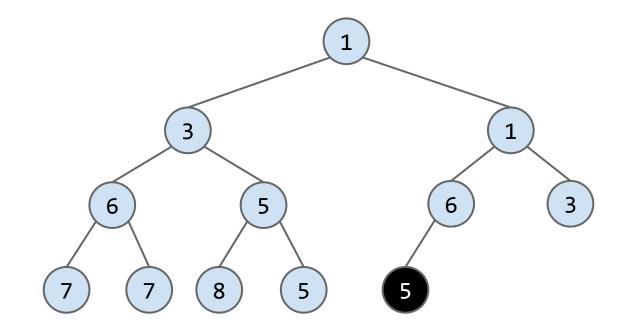
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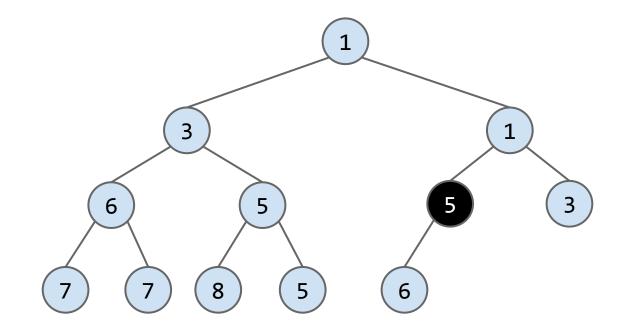
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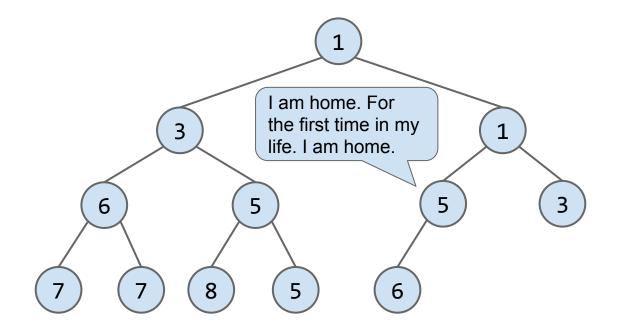
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Heap Delete

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Tree Representations

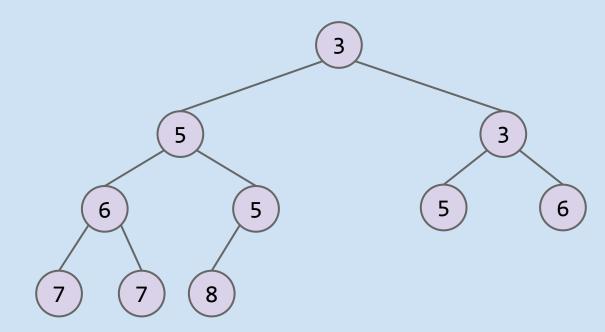
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Priority Queue Summary Data Structures Summary

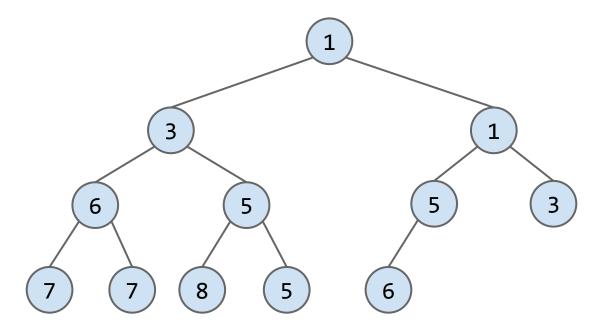


Challenge: Come up with an algorithm for removeSmallest().

Runtime must be logarithmic.

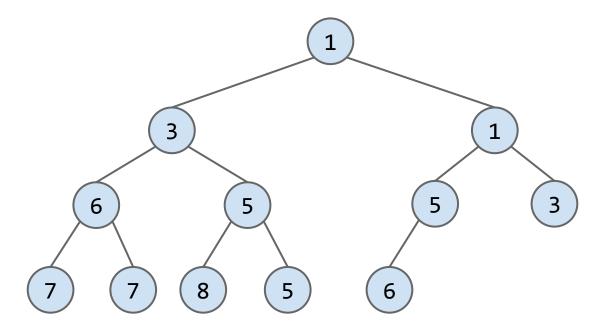






Delete min.



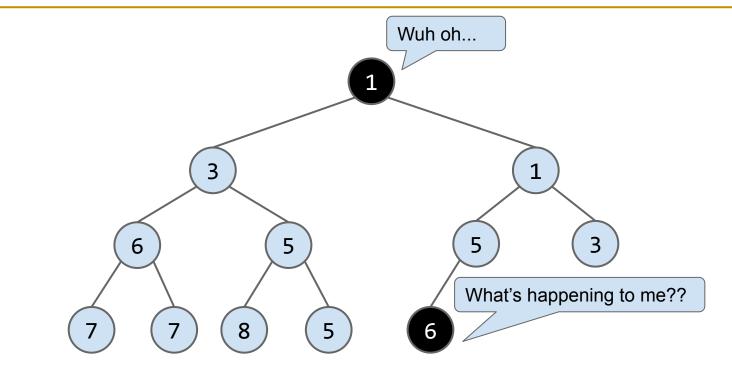


Delete min.

• Swap the last item in the heap into the root.



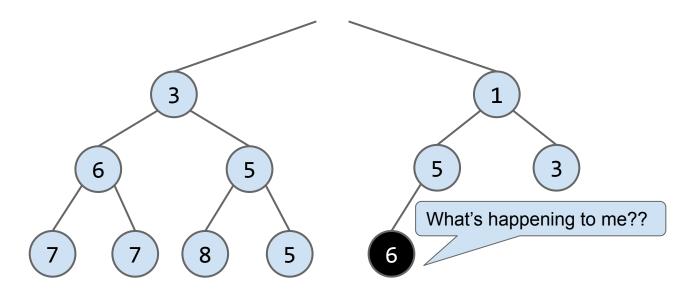
Heap Delete Demo



Delete min.

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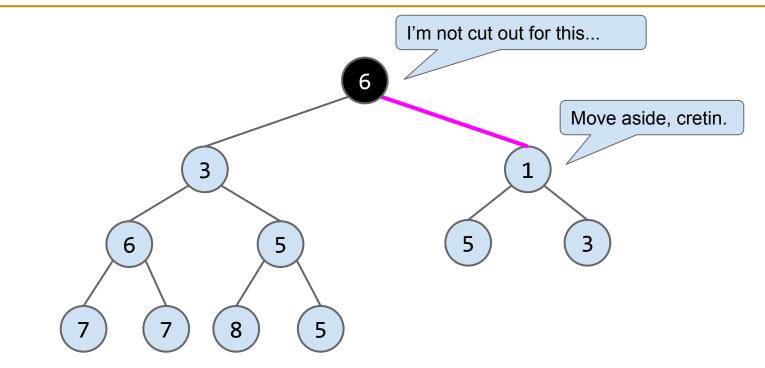


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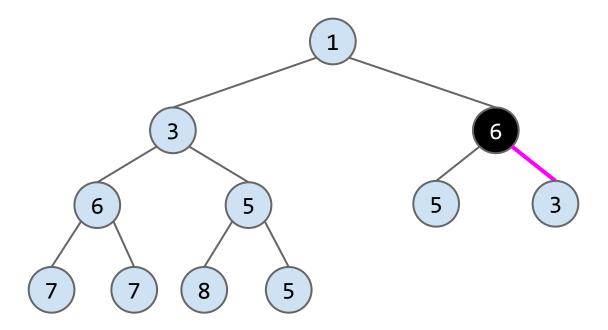
Heap Delete Demo



Delete min.

- Swap the last item in the heap into the root.
- Then sink your way down the hierarchy, yielding to most qualified folks...

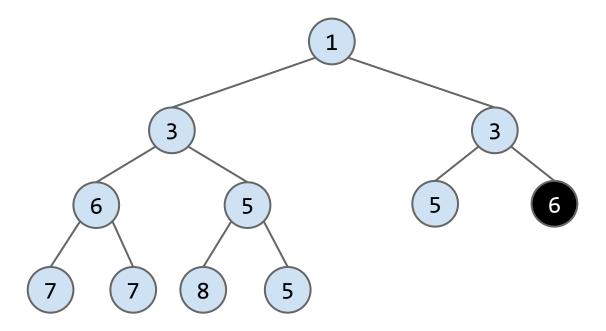




Delete min.

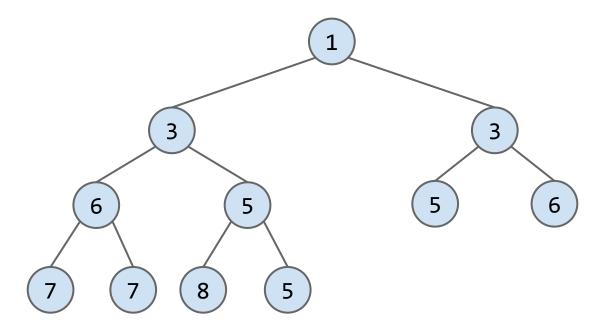
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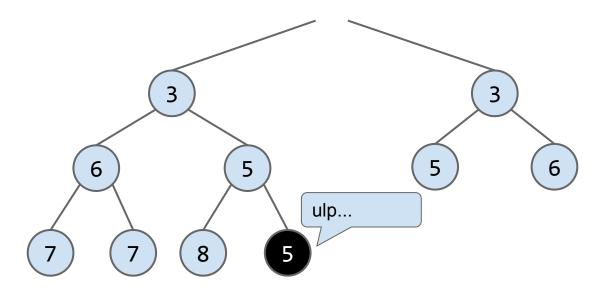
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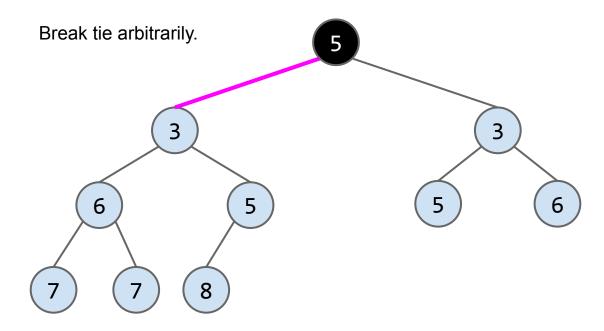
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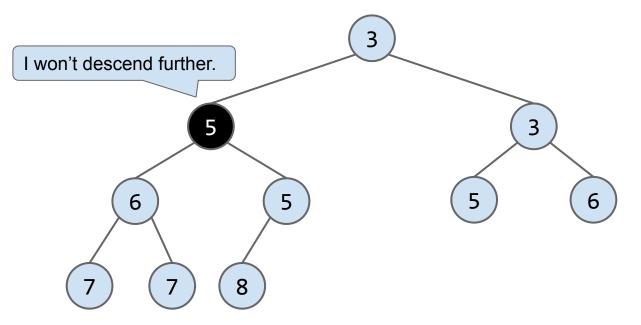
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Recursive Representation (1)

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Given a heap, how do we implement PQ operations?

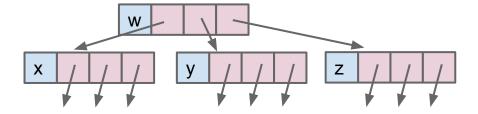
- getSmallest() return the item in the root node.
- add(x) place the new employee in the last position, and promote as high as possible.
- removeSmallest() assassinate the president (of the company), promote the rightmost person in the company to president. Then demote repeatedly, always taking the 'better' successor.

Remaining question: How would we do all this in Java?

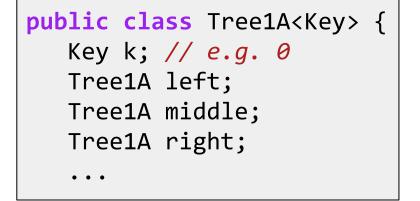


How do we Represent a Tree in Java?

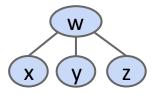
Approach 1a, 1b and 1c: Create mapping from node to children.



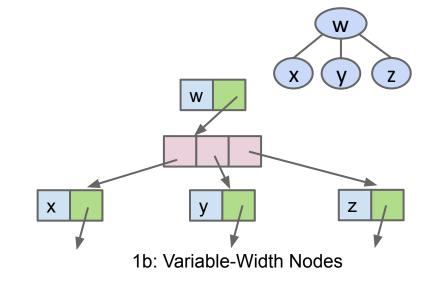
1a: Fixed-Width Nodes (BSTMap used this approach)





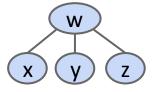


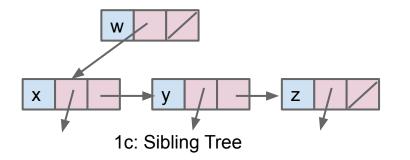
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Approach 1a, 1b and 1c: Create mapping from node to children.

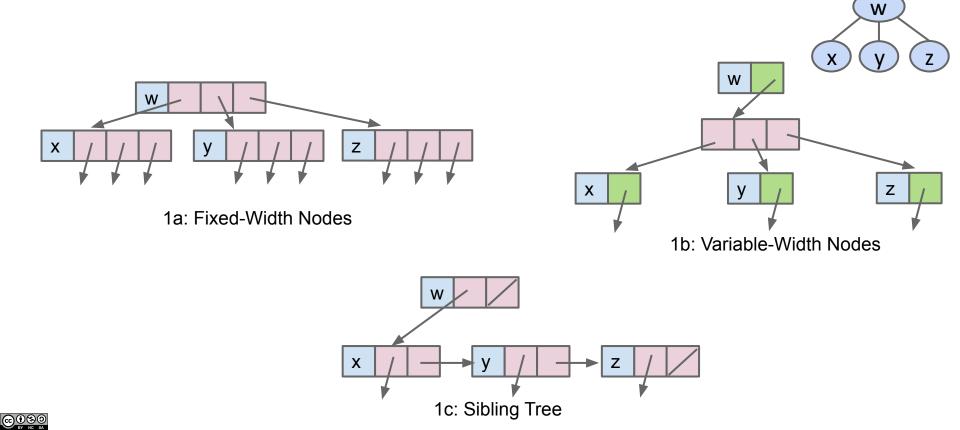






How do we Represent a Tree in Java?

Approach 1a, 1b and 1c: Create mapping from node to children.



Array Representations (2, 3, 3b)

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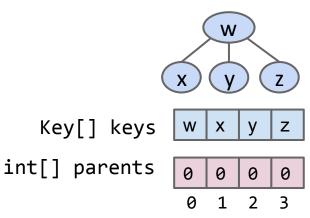


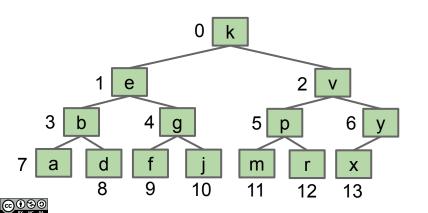
How do we Represent a Tree in Java?

Approach 2: Store keys in an array. Store parentIDs in an array.

• Similar to what we did with disjointSets.

```
public class Tree2<Key> {
   Key[] keys;
   int[] parents;
   ...
```





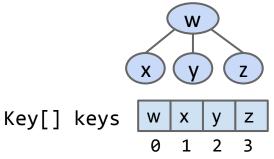


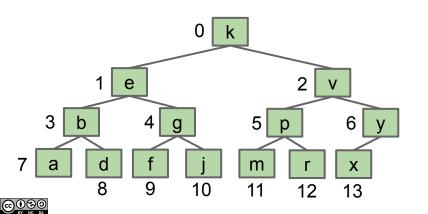
How do we Represent a Tree in Java?

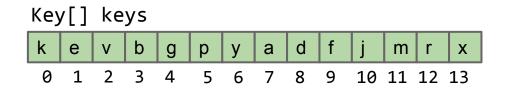
Approach 3: Store keys in an array. Don't store structure anywhere.

- To interpret array: Simply assume tree is complete.
- Obviously only works for "complete" trees.

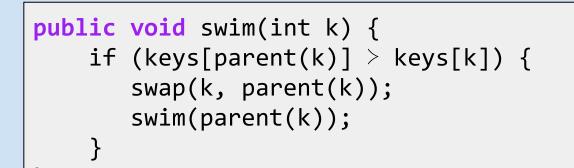
```
public class Tree3<Key> {
  Key[] keys;
  ...
```

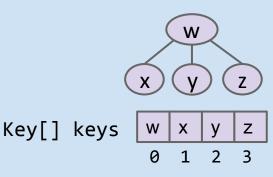


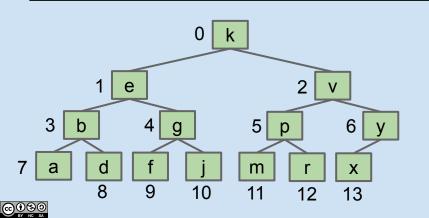


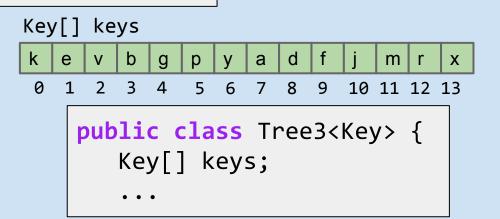


Challenge: Write the parent(k) method for approach 3.

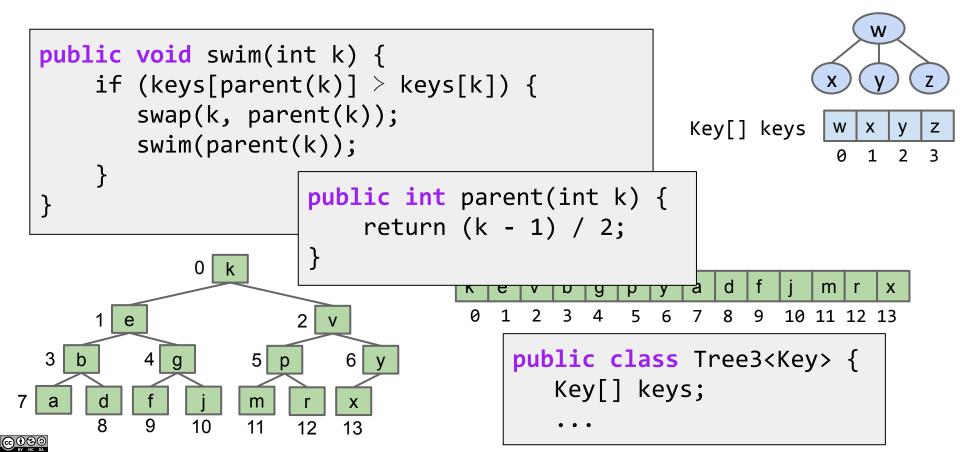


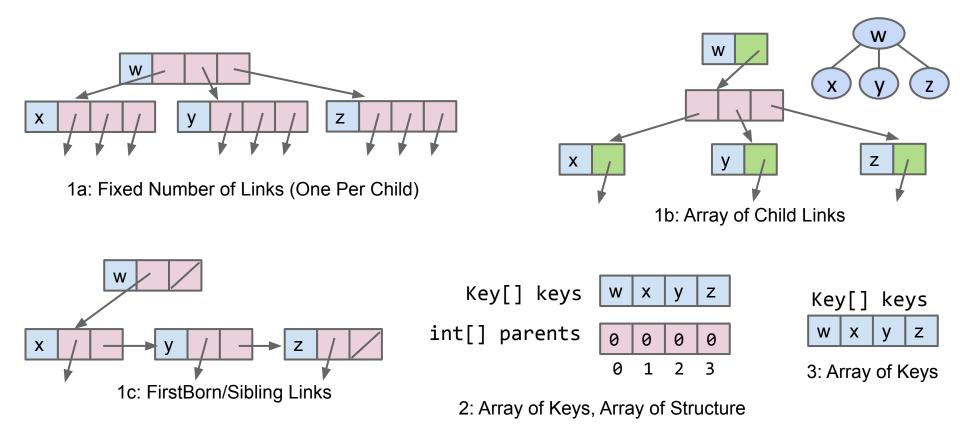






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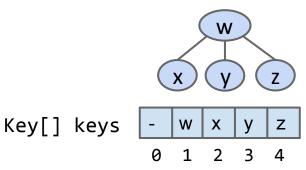


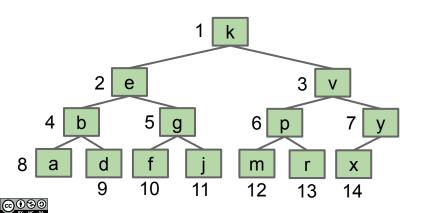


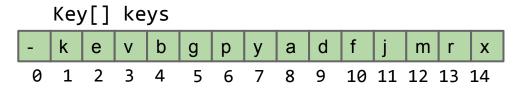
Approach 3B (book implementation): Leaving One Empty Spot

Approach 3b: Store keys in an array. Offset everything by 1 spot.

- Same as 3, but leave spot 0 empty.
- Makes computation of children/parents "nicer".
 - o leftChild(k) = k*2
 - \circ rightChild(k) = k*2 + 1
 - \circ parent(k) = k/2







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Data Structures Summary



	Ordered Array	Bushy BST	Hash Table	Неар
add	Θ(N)	Θ(log N)	Θ(1)	Θ(log N)
getSmallest	Θ(1)	Θ(log N)	Θ(N)	Θ(1)
removeSmallest	Θ(N)	Θ(log N)	Θ(N)	Θ(log N)

Notes:

Items with same priority hard to handle.

- Why "priority queue"? Can think of position in tree as its "priority."
- Heap is log N time AMORTIZED (some resizes, but no big deal).
- BST can have constant getSmallest if you keep a pointer to smallest.
- Heaps handle duplicate priorities much more naturally than BSTs.
- Array based heaps take less memory (very roughly about 1/3rd the memory of representing a tree with approach 1a).



- 1. How does a PQ know how to determine which item in a PQ is larger?
 - a. What could we change so that there is a default comparison?
- 2. What constructors are needed to allow for different orderings?

```
/** (Min) Priority Queue: Allowing tracking and removal of the
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Data Structures Summary



The Search Problem

Given a stream of data, retrieve information of interest.

- Examples:
 - Website users post to personal page. Serve content only to friends.
 - Given logs for thousands of weather stations, display weather map for specified date and time.



Recent Bulletin Board Posts from your Friends:				
From	Date	Subject		
Jojo	10/12/2004	Adam Arcuragi wants you to make out with somebody!		
Maria	10/11/2004	anyone looking for loft in greepoint?		
Larry	10/09/2004	My new band's debut - 10/16		
Jojo	10/09/2004	me and bitter, bitter weeks		

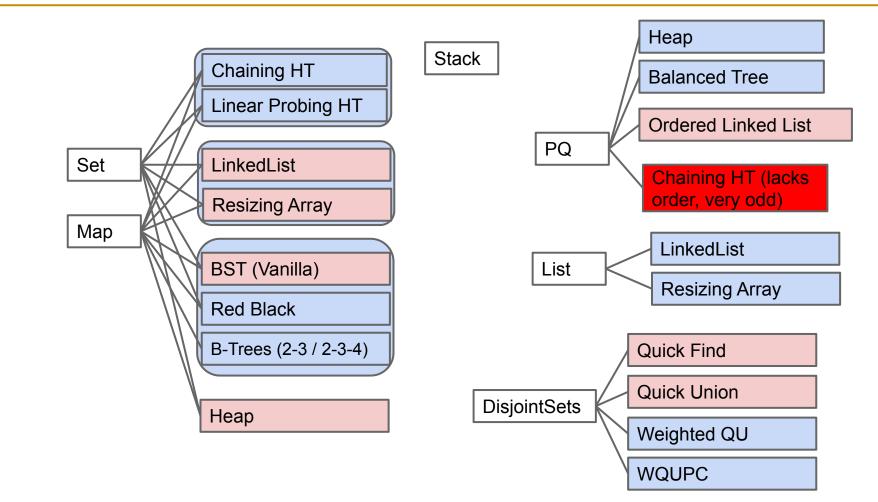




Name	Storage Operation(s)	Primary Retrieval Operation	Retrieve By:
List	add(key) insert(key, index)	get(index)	index
Мар	put(key, value)	get(key)	key identity
Set	add(key)	containsKey(key)	key identity
PQ	add(key)	<pre>getSmallest()</pre>	key order (a.k.a. key size)
Disjoint Sets	<pre>connect(int1, int2)</pre>	<pre>isConnected(int1, int2)</pre>	two int values

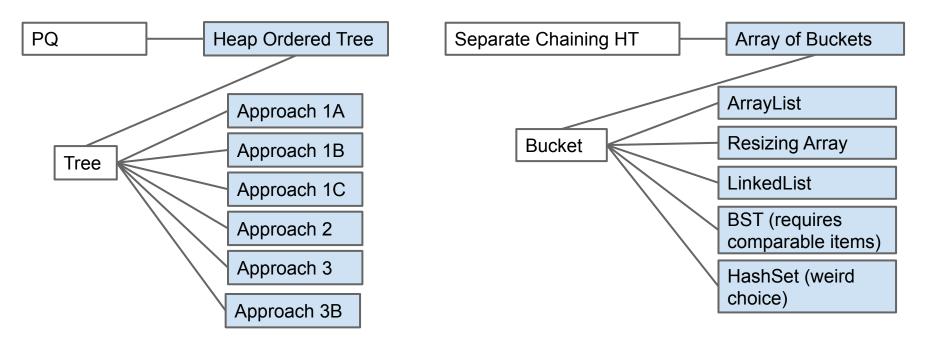


Diagram of Data Structures and ADTs (past semester version)



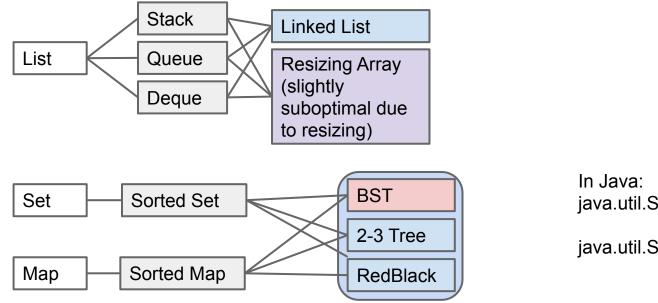


Abstraction often happens in layers!





Specialized Searching Data Structures:



java.util.SortedSet

java.util.SortedMap

PQ

Don't usually consider MinPQ and MaxPQ to be different data structures, since we can just provide the opposite comparator.



Data Structures

Data Structure: A particular way of organizing data.

- We've covered many of the most fundamental abstract data types, their common implementations, and the tradeoffs thereof.
- We'll do two more in this class:
 - Tries, graphs.

V.T.E	Data structures	[hide]
Types	Collection · Container	
Abstract	Associative array · Double-ended priority queue · Double-ended queue · List · Map · Multimap · Priority queue · Queue · Set (multiset) · Disjoint Sets · Stack	
Arrays	Bit array · Circular buffer · Dynamic array · Hash table · Hashed array tree · Sparse array	
Linked	Association list Linked list Skip list Unrolled linked list XOR linked list	
Trees	B-tree · Binary search tree (AA · AVL · red-black · self-balancing · splay) · Heap (binary · binomial · Fibonacci) · R-tree (R* · R+ · Hilbert) (Hash tree)	Trie
Graphs	Binary decision diagram · Directed acyclic graph · Directed acyclic word graph	

